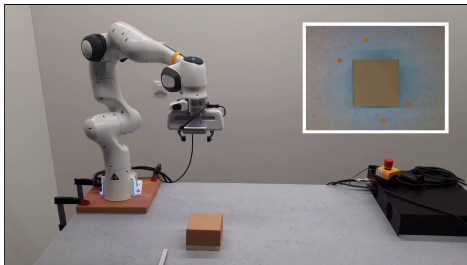
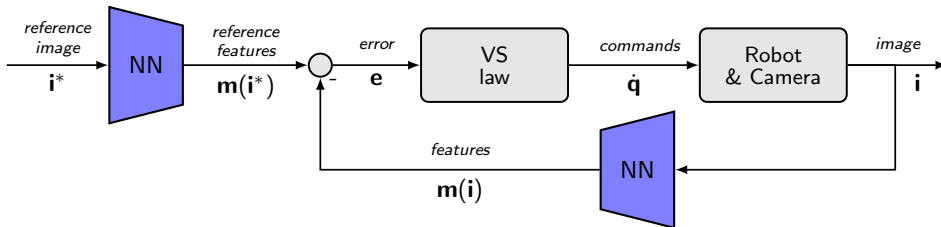


Visual Servoing with Geometrically Interpretable Neural Perception

A. Paolillo, M. Nava, D. Piga, A. Giusti - IDSIA USI/SUPSI, Lugano, Switzerland



- ▶ We provide the visual servoing scheme with a *modular* and *transferable neural perception model*
- ▶ A *deep learning* method derives *supervision* from the knowledge of the visual servoing and the features motion through several demonstrations of visual tasks
- ▶ *Simulations* and *experiments* are carried out with a robotic manipulator