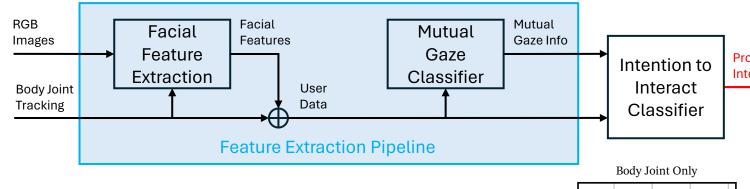
Predicting the Intention to Interact with a Service Robot: the Role of Gaze Cues

S. Arreghini, G. Abbate, A. Giusti, A. Paolillo – IDSIA USI-SUPSI, Lugano, Switzerland



- A feature extraction pipeline provides user tracking data
- A recurrent neural network estimates users' probability of interaction
- Facial features and gaze cues increase performance at all distances
- A service robot offers a chocolate treat only to interested users
- Self-supervised adaptation to novel environments

